

ROL

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Chapter 1

ROL Documentation (Development Version)

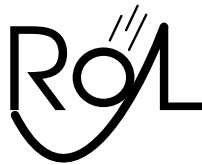


Figure 1.1: Rapid Optimization Library

1.1 Introduction

ROL, the Rapid Optimization Library, is a Trilinos package for matrix-free optimization.

1.2 Overview

Current release of ROL includes the following features:

- Unconstrained optimization algorithms.

1.3 Quick Start

The Rosenbrock example ([rol/example/rosenbrock/example_01.cpp](#)) demonstrates the use of ROL. It amounts to six steps:

1.3.1 Step 1: Implement linear algebra / vector interface.

--- or try one of the provided implementations, such as `ROL::StdVector` in `rol/vector`.

```
ROL::Vector
```

1.3.2 Step 2: Implement objective function interface.

--- or try one of the provided functions, such as `ROL::Objective_Rosenbrock` in `rol/zoo`.

```
ROL::Objective
```

1.3.3 Step 3: Choose optimization step.

--- with `ParameterList` settings in the variable `parlist`.

```
ROL::LineSearchStep<RealT> step(parlist);
```

1.3.4 Step 4: Set status test.

--- with gradient tolerance `{gtol}`, step tolerance `{stol}` and the maximum number of iterations `{maxit}`.

```
ROL::StatusTest<RealT> status(gtol, stol, maxit);
```

1.3.5 Step 5: Define an algorithm.

--- based on the status test and the step.

```
ROL::DefaultAlgorithm<RealT> algo(step, status);
```

1.3.6 Step 6: Run algorithm.

--- starting from the initial iterate `{x}`, applied to objective function `{obj}`.

```
algo.run(x, obj);
```


1.3.7 Done!

1.4 Development Plans

Constrained optimization, optimization under uncertainty, etc.

Chapter 2

Class Index

2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

ROL::Algorithm	11
ROL::AlgorithmState< Real >	12
ROL::DefaultAlgorithm< Real >	14
ROL::Krylov< Real >	17
ROL::LineSearch< Real >	20
ROL::NonlinearCG< Real >	25
ROL::NonlinearCGState< Real >	26
ROL::Objective< Real >	27
ROL::Objective_Beale< Real >	29
ROL::Objective_FreudensteinRoth< Real >	31
ROL::Objective_LeastSquares< Real >	32
ROL::Objective_PoissonControl< Real >	33
ROL::Objective_PoissonInversion< Real >	35
ROL::Objective_Powell< Real >	37
ROL::Objective_Rosenbrock< Real >	38
ROL::Objective_SumOfSquares< Real >	40
ROL::Secant< Real >	41
ROL::BarzilaiBorwein< Real >	13
ROL::IBFGS< Real >	18
ROL::IDFP< Real >	19
ROL::ISR1< Real >	24
ROL::SecantState< Real >	42
ROL::StatusTest< Real >	43
ROL::Step< Real >	46
ROL::LineSearchStep< Real >	22

ROL::TrustRegionStep< Real >	51
ROL::StepState< Real >	48
ROL::TrustRegion< Real >	49
ROL::Vector< Real >	53
ROL::EpetraMultiVector< Real >	15
ROL::StdVector< Real, Element >	44

Chapter 3

Class Index

3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

ROL::Algorithm (Provides an interface to run optimization algorithms) . . .	11
ROL::AlgorithmState< Real >	12
ROL::BarzilaiBorwein< Real > (Provides definitions for Barzilai-Borwein operators)	13
ROL::DefaultAlgorithm< Real >	14
ROL::EpetraMultiVector< Real > (Implements the ROL::Vector interface for an Epetra_MultiVector)	15
ROL::Krylov< Real > (Provides definitions for Krylov solvers)	17
ROL::LBFGS< Real > (Provides definitions for limited-memory BFGS operators)	18
ROL::IDFP< Real > (Provides definitions for limited-memory DFP operators)	19
ROL::LineSearch< Real > (Provides interface for and implements line searches)	20
ROL::LineSearchStep< Real > (Provides the interface to compute optimization steps with line search)	22
ROL::LSR1< Real > (Provides definitions for limited-memory SR1 operators)	24
ROL::NonlinearCG< Real > (Implementats nonlinear conjugate gradient methods)	25
ROL::NonlinearCGState< Real >	26
ROL::Objective< Real > (Provides the interface to evaluate objective functions)	27
ROL::Objective_Beale< Real > (Beale's function)	29

ROL::Objective_FreudensteinRoth< Real > (Freudenstein and Roth's function)	31
ROL::Objective_LeastSquares< Real > (Least squares function)	32
ROL::Objective_PoissonControl< Real > (Poisson distributed control)	33
ROL::Objective_PoissonInversion< Real > (Poisson material inversion)	35
ROL::Objective_Powell< Real > (Powell's badly scaled function)	37
ROL::Objective_Rosenbrock< Real > (Rosenbrock's function)	38
ROL::Objective_SumOfSquares< Real > (Sum of squares function)	40
ROL::Secant< Real > (Provides interface for and implements limited-memory secant operators)	41
ROL::SecantState< Real >	42
ROL::StatusTest< Real > (Provides an interface to check status of optimization algorithms)	43
ROL::StdVector< Real, Element > (Provides the std::vector implementation of the ROL::Vector interface)	44
ROL::Step< Real > (Provides the interface to compute optimization steps)	46
ROL::StepState< Real >	48
ROL::TrustRegion< Real > (Provides interface for and implements trust-region subproblem solvers)	49
ROL::TrustRegionStep< Real > (Provides the interface to compute optimization steps with trust regions)	51
ROL::Vector< Real > (Provides the vector space interface)	53

Chapter 4

File Index

4.1 File List

Here is a list of all documented files with brief descriptions:

example_01.cpp (Shows how to minimize Rosenbrock's function using Newton-Krylov)	55
ROL_Algorithm.hpp	??
ROL_BarzilaiBorwein.hpp	??
ROL_Beale.hpp (Contains definitions for Beale's function)	57
ROL_EpetraMultiVector.hpp	??
ROL_FreudensteinRoth.hpp (Contains definitions for Freudenstein and Roth's function)	58
ROL_Krylov.hpp	??
ROL_IBFGS.hpp	??
ROL_IDFP.hpp	??
ROL_LeastSquares.hpp (Contains definitions for least squares function) . . .	59
ROL_LineSearch.hpp	??
ROL_LineSearchStep.hpp	??
ROL_ISR1.hpp	??
ROL_NonlinearCG.hpp	??
ROL_Objective.hpp	??
ROL_ObjectiveDef.hpp	??
ROL_PoissonControl.hpp (Contains definitions for Poisson optimal control) .	60
ROL_PoissonInversion.hpp (Contains definitions for Poisson material inversion)	61
ROL_Powell.hpp (Contains definitions for Powell's badly scaled function) .	62
ROL_Rosenbrock.hpp (Contains definitions for Rosenbrock's function) . . .	63
ROL_Secant.hpp	??
ROL_StatusTest.hpp	??

ROL_StdVector.hpp	??
ROL_Step.hpp	??
ROL_SumOfSquares.hpp (Contains definitions for sum of squares function)	64
ROL_TestObjectives.hpp (Contains definitions of test objective functions)	65
ROL_TrustRegion.hpp	??
ROL_TrustRegionStep.hpp	??
ROL_Types.hpp (Contains definitions of custom data types in ROL)	66
ROL_Vector.hpp	??
function/test_01.cpp	??
step/test_01.cpp	??
vector/test_01.cpp	??
step/test_02.cpp	??
vector/test_02.cpp	??

Chapter 5

Class Documentation

5.1 ROL::Algorithm Class Reference

Provides an interface to run optimization algorithms.

```
#include <ROL_Algorithm.hpp>
```

5.1.1 Detailed Description

Provides an interface to run optimization algorithms.

The documentation for this class was generated from the following file:

- ROL_Algorithm.hpp

5.2 ROL::AlgorithmState< Real > Struct Template Reference

Public Attributes

- int **iter**
- int **nfval**
- int **ngrad**
- Real **value**
- Real **gnorm**
- Real **snorm**
- Teuchos::RCP< [Vector](#)< Real > > **iterateVec**

5.2.1 Detailed Description

`template<class Real> struct ROL::AlgorithmState< Real >`

Definition at line 58 of file ROL_Step.hpp.

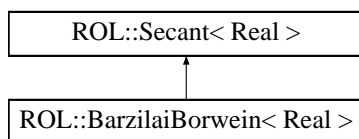
The documentation for this struct was generated from the following file:

- ROL_Step.hpp

5.3 ROL::BarzilaiBorwein< Real > Class Template Reference

Provides definitions for Barzilai-Borwein operators.

```
#include <ROL_BarzilaiBorwein.hpp>Inheritance diagram for ROL::BarzilaiBorwein< Real >::
```



Public Member Functions

- **BarzilaiBorwein** (int type=1)
- void **applyH** (Vector< Real > &Hv, const Vector< Real > &v, const Vector< Real > &x)
- void **applyB** (Vector< Real > &Bv, const Vector< Real > &v, const Vector< Real > &x)

Private Attributes

- int **type_**

5.3.1 Detailed Description

template<class Real> class ROL::BarzilaiBorwein< Real >

Provides definitions for Barzilai-Borwein operators.

Definition at line 54 of file ROL_BarzilaiBorwein.hpp.

The documentation for this class was generated from the following file:

- ROL_BarzilaiBorwein.hpp

5.4 ROL::DefaultAlgorithm< Real > Class Template Reference

Public Member Functions

- **DefaultAlgorithm** ([Step](#)< Real > &step, [StatusTest](#)< Real > &status, bool printHeader=false)
- virtual std::vector< std::string > [run](#) ([Vector](#)< Real > &x, [Objective](#)< Real > &obj, bool print=false)
Run algorithm.
- std::string [getIterHeader](#) (void)
- std::string [getIterInfo](#) (bool withHeader=false)

Private Attributes

- Teuchos::RCP< [Step](#)< Real > > [step_](#)
- Teuchos::RCP< [StatusTest](#)< Real > > [status_](#)
- Teuchos::RCP< [AlgorithmState](#)< Real > > [state_](#)
- bool [printHeader_](#)

5.4.1 Detailed Description

template<class Real> class ROL::DefaultAlgorithm< Real >

Definition at line 58 of file ROL_Algorithm.hpp.

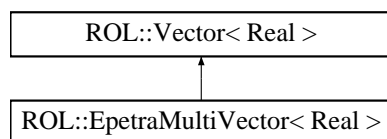
The documentation for this class was generated from the following file:

- ROL_Algorithm.hpp

5.5 ROL::EpetraMultiVector< Real > Class Template Reference

Implements the [ROL::Vector](#) interface for an Epetra_MultiVector.

#include <ROL_EpetraMultiVector.hpp> Inheritance diagram for ROL::EpetraMultiVector< Real >::



Public Member Functions

- **EpetraMultiVector** (const Teuchos::RCP< Epetra_MultiVector > &epetra_vec)
- void **plus** (const [Vector](#)< Real > &x)
*Compute $y \leftarrow x + y$ where $y = *this$.*
- void **scale** (const Real alpha)
*Compute $y \leftarrow \alpha y$ where $y = *this$.*
- Real **dot** (const [Vector](#)< Real > &x) const
*Returns $\langle y, x \rangle$ where $y = *this$.*
- Real **norm** () const
*Returns $\|y\|$ where $y = *this$.*
- Teuchos::RCP< [Vector](#)< Real > > **clone** () const
Clone to make a new (uninitialized) vector.
- virtual void **axpy** (const Real alpha, const [Vector](#)< Real > &x)
*Compute $y \leftarrow \alpha x + y$ where $y = *this$.*
- virtual void **zero** ()
Set to zero vector.
- virtual void **set** (const [Vector](#)< Real > &x)
*Set $y \leftarrow x$ where $y = *this$.*

- Teuchos::RCP< const Epetra_MultiVector > **getVector** () const
- Teuchos::RCP< [Vector](#)< Real > > **basis** (const int i) const
Return i-th basis vector: define if finite-difference gradients and Hessians are used.
- int **dimension** () const

Private Attributes

- Teuchos::RCP< Epetra_MultiVector > **epetra_vec_**

5.5.1 Detailed Description

template<class Real> class ROL::EpetraMultiVector< Real >

Implements the [ROL::Vector](#) interface for an Epetra_MultiVector.

Definition at line 61 of file ROL_EpetraMultiVector.hpp.

The documentation for this class was generated from the following file:

- ROL_EpetraMultiVector.hpp

5.6 ROL::Krylov< Real > Class Template Reference

Provides definitions for [Krylov](#) solvers.

```
#include <ROL_Krylov.hpp>
```

Public Member Functions

- **Krylov** (Real tol1=1.e-4, Real tol2=1.e-2, int maxit=100, bool useInexact=false)
- void **CG** ([Vector](#)< Real > &s, int &iter, int &flag, const [Vector](#)< Real > &g, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj, Teuchos::RCP< [Secant](#)< Real > > secant=Teuchos::null)

Private Attributes

- Real **tol1_**
- Real **tol2_**
- int **maxit_**
- bool **useInexact_**

5.6.1 Detailed Description

template<class Real> class ROL::Krylov< Real >

Provides definitions for [Krylov](#) solvers.

Definition at line 54 of file ROL_Krylov.hpp.

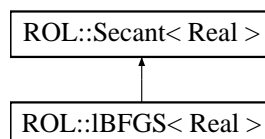
The documentation for this class was generated from the following file:

- ROL_Krylov.hpp

5.7 ROL::IBFGS< Real > Class Template Reference

Provides definitions for limited-memory BFGS operators.

#include <ROL_IBFGS.hpp> Inheritance diagram for ROL::IBFGS< Real >::



Public Member Functions

- **IBFGS** (int M)
- void **applyH** (Vector< Real > &Hv, const Vector< Real > &v, const Vector< Real > &x)
- void **applyB** (Vector< Real > &Bv, const Vector< Real > &v, const Vector< Real > &x)

5.7.1 Detailed Description

template<class Real> class ROL::IBFGS< Real >

Provides definitions for limited-memory BFGS operators.

Definition at line 54 of file ROL_IBFGS.hpp.

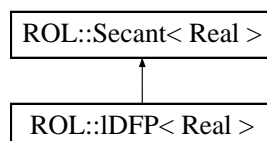
The documentation for this class was generated from the following file:

- ROL_IBFGS.hpp

5.8 ROL::IDFP< Real > Class Template Reference

Provides definitions for limited-memory DFP operators.

#include <ROL_IDFP.hpp> Inheritance diagram for ROL::IDFP< Real >::



Public Member Functions

- **IDFP** (int M)
- void **applyH** (Vector< Real > &Hv, const Vector< Real > &v, const Vector< Real > &x)
- virtual void **applyH0** (Vector< Real > &Hv, const Vector< Real > &v, const Vector< Real > &x)
- void **applyB** (Vector< Real > &Bv, const Vector< Real > &v, const Vector< Real > &x)
- virtual void **applyB0** (Vector< Real > &Bv, const Vector< Real > &v, const Vector< Real > &x)

5.8.1 Detailed Description

template<class Real> class ROL::IDFP< Real >

Provides definitions for limited-memory DFP operators.

Definition at line 54 of file ROL_IDFP.hpp.

The documentation for this class was generated from the following file:

- ROL_IDFP.hpp

5.9 ROL::LineSearch< Real > Class Template Reference

Provides interface for and implements line searches.

```
#include <ROL_LineSearch.hpp>
```

Public Member Functions

- **LineSearch** (Teuchos::ParameterList &parlist)
- bool **status** (const ELineSearch type, int &ls_neval, int &ls_ngrad, const Real alpha, const Real fold, const Real sgold, const Real fnew, const [Vector](#)< Real > &x, const [Vector](#)< Real > &s, [Objective](#)< Real > &obj)
- void **run** (Real &alpha, Real &fval, int &ls_neval, int &ls_ngrad, const Real &gs, const [Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)
- void **simplebacktracking** (Real &alpha, Real &fval, int &ls_neval, int &ls_ngrad, const Real &gs, const [Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)
- void **backtracking** (Real &alpha, Real &fval, int &ls_neval, int &ls_ngrad, const Real &gs, const [Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)
- void **bisection** (Real &alpha, Real &fval, int &ls_neval, int &ls_ngrad, const Real &gs, const [Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)
- void **goldensection** (Real &alpha, Real &fval, int &ls_neval, int &ls_ngrad, const Real &gs, const [Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)
- void **brents** (Real &alpha, Real &fval, int &ls_neval, int &ls_ngrad, const Real &gs, const [Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)

Private Attributes

- ELineSearch **els_**
- ECurvatureCondition **econd_**
- EDescent **edesc_**
- int **maxit_**
- Real **c1_**
- Real **c2_**
- Real **tol_**
- Real **rho_**
- Real **alpha0_**
- bool **useralpha_**

5.9.1 Detailed Description

template<class Real> class ROL::LineSearch< Real >

Provides interface for and implements line searches.

Definition at line 54 of file ROL_LineSearch.hpp.

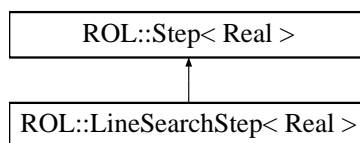
The documentation for this class was generated from the following file:

- ROL_LineSearch.hpp

5.10 ROL::LineSearchStep< Real > Class Template Reference

Provides the interface to compute optimization steps with line search.

#include <ROL_LineSearchStep.hpp> Inheritance diagram for ROL::LineSearchStep< Real >::



Public Member Functions

- **LineSearchStep** (Teuchos::ParameterList &parlist)
- **LineSearchStep** (Teuchos::RCP< [Secant](#)< Real > > &secant, Teuchos::ParameterList &parlist)
- void [compute](#) ([Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj, [AlgorithmState](#)< Real > &algo_state)
Compute step.
- void [update](#) ([Vector](#)< Real > &x, const [Vector](#)< Real > &s, [Objective](#)< Real > &obj, [AlgorithmState](#)< Real > &algo_state)
Update step, if successful.
- std::string [printHeader](#) (void) const
Print iterate header.
- std::string [printName](#) (void) const
Print step name.
- std::string [print](#) ([AlgorithmState](#)< Real > &algo_state, bool printHeader=false) const
Print iterate status.

Private Attributes

- Teuchos::RCP< [Secant](#)< Real > > **secant_**
- Teuchos::RCP< [Krylov](#)< Real > > **krylov_**

- Teuchos::RCP< [NonlinearCG](#)< Real > > **nlgc_**
- Teuchos::RCP< [LineSearch](#)< Real > > **lineSearch_**
- int **iterKrylov_**
- int **flagKrylov_**
- ELineSearch **els_**
- ECurvatureCondition **econd_**
- EDescent **edesc_**
- ESecant **esec_**
- int **ls_nfval_**
- int **ls_ngrad_**
- std::vector< bool > **useInexact_**

5.10.1 Detailed Description

template<class Real> class ROL::LineSearchStep< Real >

Provides the interface to compute optimization steps with line search.

Definition at line 65 of file ROL_LineSearchStep.hpp.

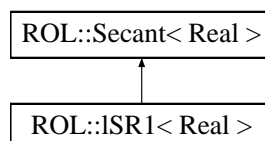
The documentation for this class was generated from the following file:

- ROL_LineSearchStep.hpp

5.11 ROL::ISR1< Real > Class Template Reference

Provides definitions for limited-memory SR1 operators.

#include <ROL_ISR1.hpp> Inheritance diagram for ROL::ISR1< Real >::



Public Member Functions

- **ISR1** (int M)
- void **update** (const [Vector](#)< Real > &grad, const [Vector](#)< Real > &gp, const [Vector](#)< Real > &s, const Real snorm, const int iter)
- virtual void **applyH0** ([Vector](#)< Real > &Hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x)
- void **applyH** ([Vector](#)< Real > &Hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x)
- virtual void **applyB0** ([Vector](#)< Real > &Bv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x)
- void **applyB** ([Vector](#)< Real > &Bv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x)

Private Attributes

- bool **updateIterate_**

5.11.1 Detailed Description

template<class Real> class ROL::ISR1< Real >

Provides definitions for limited-memory SR1 operators.

Definition at line 54 of file ROL_ISR1.hpp.

The documentation for this class was generated from the following file:

- ROL_ISR1.hpp

5.12 ROL::NonlinearCG< Real > Class Template Reference

Implementats nonlinear conjugate gradient methods.

```
#include <ROL_NonlinearCG.hpp>
```

Public Member Functions

- **NonlinearCG** (ENonlinearCG type, int restart=100)
- Teuchos::RCP< [NonlinearCGState](#)< Real > > & **get_state** ()
- virtual void **run** ([Vector](#)< Real > &s, const [Vector](#)< Real > &g, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)

Private Attributes

- Teuchos::RCP< [NonlinearCGState](#)< Real > > **state_**

5.12.1 Detailed Description

template<class Real> class ROL::NonlinearCG< Real >

Implementats nonlinear conjugate gradient methods.

Definition at line 65 of file ROL_NonlinearCG.hpp.

The documentation for this class was generated from the following file:

- ROL_NonlinearCG.hpp

5.13 ROL::NonlinearCGState< Real > Struct Template Reference

Public Attributes

- `std::vector< Teuchos::RCP< Vector< Real > > > grad`
- `std::vector< Teuchos::RCP< Vector< Real > > > pstep`
- `int iter`
- `int restart`
- `ENonlinearCG nlcg_type`

5.13.1 Detailed Description

`template<class Real> struct ROL::NonlinearCGState< Real >`

Definition at line 56 of file `ROL_NonlinearCG.hpp`.

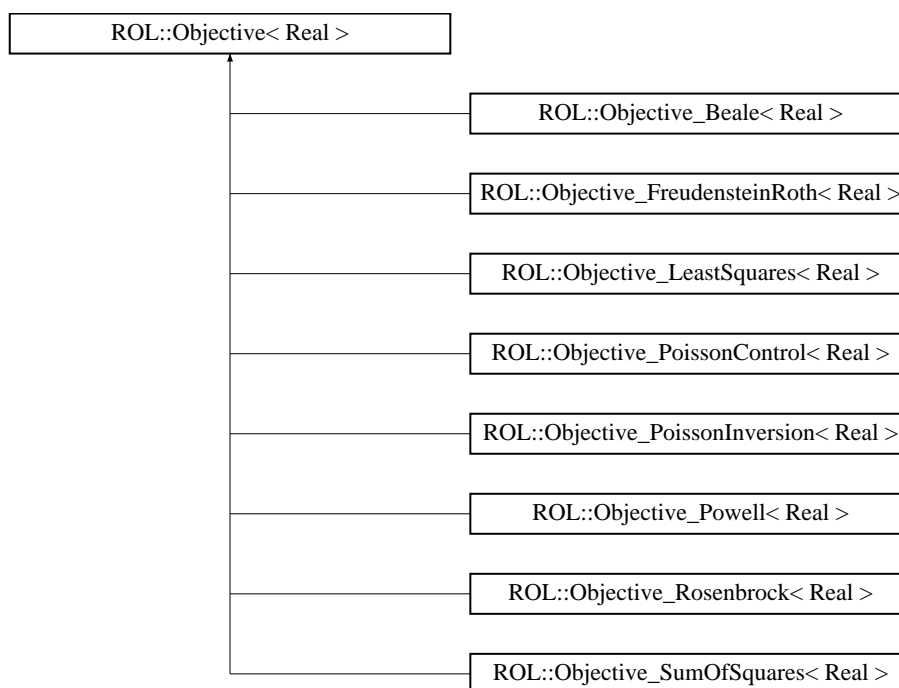
The documentation for this struct was generated from the following file:

- `ROL_NonlinearCG.hpp`

5.14 ROL::Objective< Real > Class Template Reference

Provides the interface to evaluate objective functions.

`#include <ROL_Objective.hpp>` Inheritance diagram for ROL::Objective< Real >::



Public Member Functions

- virtual Real **value** (const **Vector**< Real > &x, Real &tol)=0
Compute value.
- virtual void **gradient** (**Vector**< Real > &g, const **Vector**< Real > &x, Real &tol)
Compute gradient.
- virtual Real **dirDeriv** (const **Vector**< Real > &x, const **Vector**< Real > &d, Real &tol)
Compute directional derivative.

- virtual void `hessVec` (`Vector< Real > &hv`, const `Vector< Real > &v`, const `Vector< Real > &x`, `Real &tol`)
Apply Hessian approximation to vector.
- virtual void `invHessVec` (`Vector< Real > &hv`, const `Vector< Real > &v`, const `Vector< Real > &x`, `Real &tol`)
Apply inverse Hessian approximation to vector.
- virtual void `precond` (`Vector< Real > &Pv`, const `Vector< Real > &v`, const `Vector< Real > &x`)
Apply preconditioner to vector.
- virtual `std::vector< std::vector< Real > >` `checkGradient` (const `Vector< Real > &x`, const `Vector< Real > &d`, const bool `printToScreen=true`, const int `numSteps=ROL_NUM_CHECKDERIV_STEPS`)
Finite-difference gradient check.
- virtual `std::vector< std::vector< Real > >` `checkHessVec` (const `Vector< Real > &x`, const `Vector< Real > &v`, const bool `printToScreen=true`, const int `numSteps=ROL_NUM_CHECKDERIV_STEPS`)
Finite-difference Hessian-applied-to-vector check.

5.14.1 Detailed Description

template<class Real> class ROL::Objective< Real >

Provides the interface to evaluate objective functions. Provides the definition of the objective function interface.

Definition at line 59 of file `ROL_Objective.hpp`.

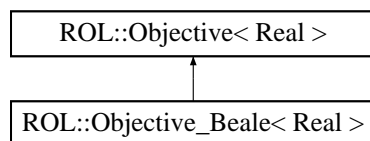
The documentation for this class was generated from the following files:

- `ROL_Objective.hpp`
- `ROL_ObjectiveDef.hpp`

5.15 ROL::Objective_Beale< Real > Class Template Reference

Beale's function.

`#include <ROL_Beale.hpp>` Inheritance diagram for ROL::Objective_Beale< Real >::



Public Member Functions

- Real **value** (const **Vector**< Real > &x, Real &tol)
Compute value.
- void **gradient** (**Vector**< Real > &g, const **Vector**< Real > &x, Real &tol)
Compute gradient.
- void **hessVec** (**Vector**< Real > &hv, const **Vector**< Real > &v, const **Vector**< Real > &x, Real &tol)
Apply Hessian approximation to vector.
- void **invHessVec** (**Vector**< Real > &hv, const **Vector**< Real > &v, const **Vector**< Real > &x, Real &tol)
Apply inverse Hessian approximation to vector.

Private Attributes

- std::vector< Real > **y_**

5.15.1 Detailed Description

`template<class Real> class ROL::Objective_Beale< Real >`

Beale's function.

Definition at line 64 of file ROL_Beale.hpp.

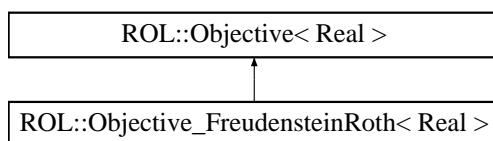
The documentation for this class was generated from the following file:

- [ROL_Beale.hpp](#)

5.16 ROL::Objective_FreudensteinRoth< Real > Class Template Reference

Freudenstein and Roth's function.

`#include <ROL_FreudensteinRoth.hpp>` Inheritance diagram for ROL::Objective_FreudensteinRoth< Real >::



Public Member Functions

- Real **value** (const **Vector**< Real > &x, Real &tol)
Compute value.
- void **gradient** (**Vector**< Real > &g, const **Vector**< Real > &x, Real &tol)
Compute gradient.
- void **hessVec** (**Vector**< Real > &hv, const **Vector**< Real > &v, const **Vector**< Real > &x, Real &tol)
Apply Hessian approximation to vector.
- void **invHessVec** (**Vector**< Real > &hv, const **Vector**< Real > &v, const **Vector**< Real > &x, Real &tol)
Apply inverse Hessian approximation to vector.

5.16.1 Detailed Description

template<class Real> class ROL::Objective_FreudensteinRoth< Real >

Freudenstein and Roth's function.

Definition at line 64 of file ROL_FreudensteinRoth.hpp.

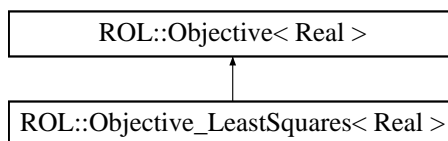
The documentation for this class was generated from the following file:

- [ROL_FreudensteinRoth.hpp](#)

5.17 ROL::Objective_LeastSquares< Real > Class Template Reference

Least squares function.

#include <ROL_LeastSquares.hpp> Inheritance diagram for ROL::Objective_LeastSquares< Real >::



Public Member Functions

- Real [value](#) (const [Vector](#)< Real > &x, Real &tol)
Compute value.
- void [gradient](#) ([Vector](#)< Real > &g, const [Vector](#)< Real > &x, Real &tol)
Compute gradient.
- void [hessVec](#) ([Vector](#)< Real > &hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x, Real &tol)
Apply Hessian approximation to vector.

5.17.1 Detailed Description

template<class Real> class ROL::Objective_LeastSquares< Real >

Least squares function.

Definition at line 64 of file ROL_LeastSquares.hpp.

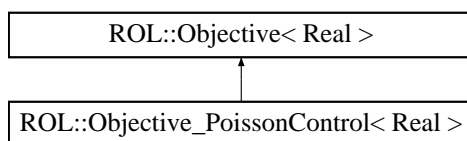
The documentation for this class was generated from the following file:

- [ROL_LeastSquares.hpp](#)

5.18 ROL::Objective_PoissonControl< Real > Class Template Reference

Poisson distributed control.

`#include <ROL_PoissonControl.hpp>` Inheritance diagram for ROL::Objective_PoissonControl< Real >::



Public Member Functions

- **Objective_PoissonControl** (Real alpha=1.e-4)
- void **apply_mass** (Vector< Real > &Mz, const Vector< Real > &z)
- void **solve_poisson** (Vector< Real > &u, const Vector< Real > &z)
- Real **evaluate_target** (Real x)
- Real **value** (const Vector< Real > &z, Real &tol)
Compute value.
- void **gradient** (Vector< Real > &g, const Vector< Real > &z, Real &tol)
Compute gradient.
- void **hessVec** (Vector< Real > &hv, const Vector< Real > &v, const Vector< Real > &z, Real &tol)
Apply Hessian approximation to vector.

Private Attributes

- Real **alpha_**

5.18.1 Detailed Description

`template<class Real> class ROL::Objective_PoissonControl< Real >`

Poisson distributed control.

Definition at line 64 of file ROL_PoissonControl.hpp.

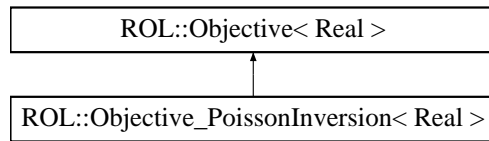
The documentation for this class was generated from the following file:

- [ROL_PoissonControl.hpp](#)

5.19 ROL::Objective_PoissonInversion< Real > Class Template Reference

Poisson material inversion.

#include <ROL_PoissonInversion.hpp> Inheritance diagram for ROL::Objective_PoissonInversion< Real >::



Public Member Functions

- **Objective_PoissonInversion** (int nz=32, Real alpha=1.e-4)
- Real **reg_value** (const [Vector](#)< Real > &z)
- void **reg_gradient** ([Vector](#)< Real > &g, const [Vector](#)< Real > &z)
- void **reg_hessVec** ([Vector](#)< Real > &hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &z)
- void **apply_mass** ([Vector](#)< Real > &Mf, const [Vector](#)< Real > &f)
- void **solve_poisson** ([Vector](#)< Real > &u, const [Vector](#)< Real > &z, [Vector](#)< Real > &b)
- Real **evaluate_target** (Real x)
- void **apply_linearized_control_operator** ([Vector](#)< Real > &Bd, const [Vector](#)< Real > &z, const [Vector](#)< Real > &d, const [Vector](#)< Real > &u)
- void **apply_transposed_linearized_control_operator** ([Vector](#)< Real > &Bd, const [Vector](#)< Real > &z, const [Vector](#)< Real > &d, const [Vector](#)< Real > &u)
- void **apply_transposed_linearized_control_operator_2** ([Vector](#)< Real > &Bd, const [Vector](#)< Real > &z, const [Vector](#)< Real > &v, const [Vector](#)< Real > &d, const [Vector](#)< Real > &u)
- void **solve_state_equation** ([Vector](#)< Real > &u, const [Vector](#)< Real > &z)
- void **solve_adjoint_equation** ([Vector](#)< Real > &p, const [Vector](#)< Real > &u, const [Vector](#)< Real > &z)
- void **solve_state_sensitivity_equation** ([Vector](#)< Real > &w, const [Vector](#)< Real > &v, const [Vector](#)< Real > &u, const [Vector](#)< Real > &z)
- void **solve_adjoint_sensitivity_equation** ([Vector](#)< Real > &q, const [Vector](#)< Real > &w, const [Vector](#)< Real > &v, const [Vector](#)< Real > &p, const [Vector](#)< Real > &u, const [Vector](#)< Real > &z)
- Real **value** (const [Vector](#)< Real > &z, Real &tol)

Compute value.

- void [gradient](#) ([Vector](#)< Real > &g, const [Vector](#)< Real > &z, Real &tol)
Compute gradient.
- void [hessVec](#) ([Vector](#)< Real > &hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &z, Real &tol)
Apply Hessian approximation to vector.

Private Attributes

- int **nu_**
- int **nz_**
- Real **hu_**
- Real **hz_**
- Real **alpha_**
- Real **eps_**
- int **reg_type_**

5.19.1 Detailed Description

template<class Real> class ROL::Objective_PoissonInversion< Real >

Poisson material inversion.

Definition at line 66 of file ROL_PoissonInversion.hpp.

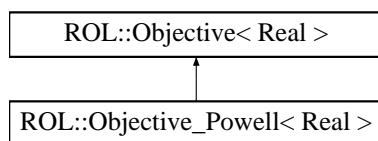
The documentation for this class was generated from the following file:

- [ROL_PoissonInversion.hpp](#)

5.20 ROL::Objective_Powell< Real > Class Template Reference

Powell's badly scaled function.

#include <ROL_Powell.hpp> Inheritance diagram for ROL::Objective_Powell< Real >::



Public Member Functions

- Real [value](#) (const [Vector](#)< Real > &x, Real &tol)
Compute value.
- void [gradient](#) ([Vector](#)< Real > &g, const [Vector](#)< Real > &x, Real &tol)
Compute gradient.
- void [hessVec](#) ([Vector](#)< Real > &hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x, Real &tol)
Apply Hessian approximation to vector.
- void [invHessVec](#) ([Vector](#)< Real > &hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x, Real &tol)
Apply inverse Hessian approximation to vector.

5.20.1 Detailed Description

template<class Real> class ROL::Objective_Powell< Real >

Powell's badly scaled function.

Definition at line 64 of file ROL_Powell.hpp.

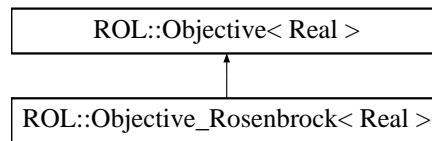
The documentation for this class was generated from the following file:

- [ROL_Powell.hpp](#)

5.21 ROL::Objective_Rosenbrock< Real > Class Template Reference

Rosenbrock's function.

`#include <ROL_Rosenbrock.hpp>` Inheritance diagram for ROL::Objective_Rosenbrock< Real >::



Public Member Functions

- **Objective_Rosenbrock** (Real alpha=100.0)
- Real **value** (const **Vector**< Real > &x, Real &tol)
Compute value.
- void **gradient** (**Vector**< Real > &g, const **Vector**< Real > &x, Real &tol)
Compute gradient.
- void **hessVec** (**Vector**< Real > &hv, const **Vector**< Real > &v, const **Vector**< Real > &x, Real &tol)
Apply Hessian approximation to vector.
- void **invHessVec** (**Vector**< Real > &hv, const **Vector**< Real > &v, const **Vector**< Real > &x, Real &tol)
Apply inverse Hessian approximation to vector.

Private Attributes

- Real **alpha_**

5.21.1 Detailed Description

`template<class Real> class ROL::Objective_Rosenbrock< Real >`

Rosenbrock's function.

Definition at line 64 of file ROL_Rosenbrock.hpp.

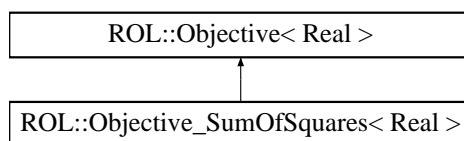
The documentation for this class was generated from the following file:

- [ROL_Rosenbrock.hpp](#)

5.22 ROL::Objective_SumOfSquares< Real > Class Template Reference

Sum of squares function.

#include <ROL_SumOfSquares.hpp> Inheritance diagram for
 ROL::Objective_SumOfSquares< Real >::



Public Member Functions

- Real [value](#) (const [Vector](#)< Real > &x, Real &tol)
Compute value.
- void [gradient](#) ([Vector](#)< Real > &g, const [Vector](#)< Real > &x, Real &tol)
Compute gradient.
- void [hessVec](#) ([Vector](#)< Real > &hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x, Real &tol)
Apply Hessian approximation to vector.
- void [invHessVec](#) ([Vector](#)< Real > &hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x, Real &tol)
Apply inverse Hessian approximation to vector.

5.22.1 Detailed Description

template<class Real> class ROL::Objective_SumOfSquares< Real >

Sum of squares function.

Definition at line 64 of file ROL_SumOfSquares.hpp.

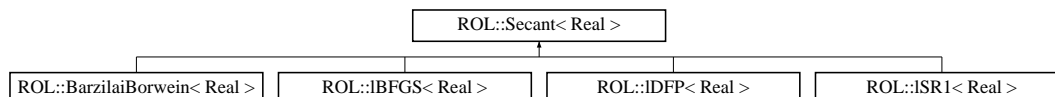
The documentation for this class was generated from the following file:

- [ROL_SumOfSquares.hpp](#)

5.23 ROL::Secant< Real > Class Template Reference

Provides interface for and implements limited-memory secant operators.

`#include <ROL_Secant.hpp>` Inheritance diagram for ROL::Secant< Real >::



Public Member Functions

- **Secant** (int M=10)
- Teuchos::RCP< SecantState< Real > > & **get_state** ()
- virtual void **update** (const Vector< Real > &grad, const Vector< Real > &gp, const Vector< Real > &s, const Real snorm, const int iter)
- virtual void **applyH** (Vector< Real > &Hv, const Vector< Real > &v, const Vector< Real > &x)=0
- virtual void **applyH0** (Vector< Real > &Hv, const Vector< Real > &v, const Vector< Real > &x)
- virtual void **applyB** (Vector< Real > &Bv, const Vector< Real > &v, const Vector< Real > &x)=0
- virtual void **applyB0** (Vector< Real > &Bv, const Vector< Real > &v, const Vector< Real > &x)
- void **test** (const Vector< Real > &x, const Vector< Real > &s)

Private Attributes

- Teuchos::RCP< SecantState< Real > > **state_**

5.23.1 Detailed Description

template<class Real> class ROL::Secant< Real >

Provides interface for and implements limited-memory secant operators.

Definition at line 67 of file ROL_Secant.hpp.

The documentation for this class was generated from the following file:

- ROL_Secant.hpp

5.24 ROL::SecantState< Real > Struct Template Reference

Public Attributes

- `std::vector< Teuchos::RCP< Vector< Real > > > iterDiff`
- `std::vector< Teuchos::RCP< Vector< Real > > > gradDiff`
- `std::vector< Real > product`
- `std::vector< Real > product2`
- `int storage`
- `int current`
- `int iter`

5.24.1 Detailed Description

`template<class Real> struct ROL::SecantState< Real >`

Definition at line 56 of file `ROL_Secant.hpp`.

The documentation for this struct was generated from the following file:

- `ROL_Secant.hpp`

5.25 ROL::StatusTest< Real > Class Template Reference

Provides an interface to check status of optimization algorithms.

```
#include <ROL_StatusTest.hpp>
```

Public Member Functions

- **StatusTest** (Real gtol=1.e-6, Real stol=1.e-12, int max_iter=100)
- virtual bool [check](#) ([AlgorithmState](#)< Real > &state)

Check algorithm status.

Private Attributes

- Real **gtol_**
- Real **stol_**
- int **max_iter_**

5.25.1 Detailed Description

```
template<class Real> class ROL::StatusTest< Real >
```

Provides an interface to check status of optimization algorithms.

Definition at line 56 of file ROL_StatusTest.hpp.

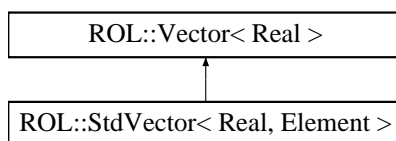
The documentation for this class was generated from the following file:

- ROL_StatusTest.hpp

5.26 ROL::StdVector< Real, Element > Class Template Reference

Provides the `std::vector` implementation of the [ROL::Vector](#) interface.

`#include <ROL_StdVector.hpp>` Inheritance diagram for `ROL::StdVector< Real, Element >::`



Public Member Functions

- **StdVector** (const Teuchos::RCP< std::vector< Element > > &std_vec)
- void **plus** (const [Vector](#)< Real > &x)
- void [scale](#) (const Real alpha)

*Compute $y \leftarrow \alpha y$ where $y = *this$.*
- Real **dot** (const [Vector](#)< Real > &x) const
- Real [norm](#) () const

*Returns $\|y\|$ where $y = *this$.*
- Teuchos::RCP< [Vector](#)< Real > > [clone](#) () const

Clone to make a new (uninitialized) vector.
- Teuchos::RCP< const std::vector< Element > > **getVector** () const
- Teuchos::RCP< [Vector](#)< Real > > [basis](#) (const int i) const

Return i -th basis vector: define if finite-difference gradients and Hessians are used.
- int [dimension](#) ()

Return dimension of the vector space.

Private Attributes

- Teuchos::RCP< std::vector< Element > > **std_vec_**

5.26.1 Detailed Description

template<class Real, class Element = Real> class ROL::StdVector< Real, Element >

Provides the std::vector implementation of the [ROL::Vector](#) interface.

Definition at line 57 of file ROL_StdVector.hpp.

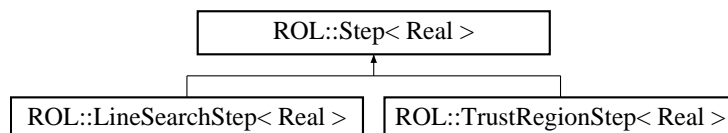
The documentation for this class was generated from the following file:

- ROL_StdVector.hpp

5.27 ROL::Step< Real > Class Template Reference

Provides the interface to compute optimization steps.

#include <ROL_Step.hpp> Inheritance diagram for ROL::Step< Real >::



Public Member Functions

- Teuchos::RCP< [StepState](#)< Real > > & **get_state** ()
- virtual void **initialize** (const [Vector](#)< Real > &x, [Objective](#)< Real > &obj, [AlgorithmState](#)< Real > &algo_state)

Initialize step.

- virtual void **compute** ([Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj, [AlgorithmState](#)< Real > &algo_state)=0

Compute step.

- virtual void **update** ([Vector](#)< Real > &x, const [Vector](#)< Real > &s, [Objective](#)< Real > &obj, [AlgorithmState](#)< Real > &algo_state)=0

Update step, if successful.

- virtual std::string **printHeader** (void) const =0

Print iterate header.

- virtual std::string **printName** (void) const =0

Print step name.

- virtual std::string **print** ([AlgorithmState](#)< Real > &algo_state, bool printHeader=false) const =0

Print iterate status.

Public Attributes

- Teuchos::RCP< [StepState](#)< Real > > **state_**

5.27.1 Detailed Description

template<class Real> class ROL::Step< Real >

Provides the interface to compute optimization steps.

Definition at line 76 of file ROL_Step.hpp.

The documentation for this class was generated from the following file:

- ROL_Step.hpp

5.28 ROL::StepState< Real > Struct Template Reference

Public Attributes

- Teuchos::RCP< [Vector](#)< Real > > **gradientVec**
- Teuchos::RCP< [Vector](#)< Real > > **descentVec**

5.28.1 Detailed Description

template<class Real> struct ROL::StepState< Real >

Definition at line 69 of file ROL_Step.hpp.

The documentation for this struct was generated from the following file:

- ROL_Step.hpp

5.29 ROL::TrustRegion< Real > Class Template Reference

Provides interface for and implements trust-region subproblem solvers.

```
#include <ROL_TrustRegion.hpp>
```

Public Member Functions

- **TrustRegion** (Teuchos::ParameterList &parlist)
- void **update** (Vector< Real > &x, Real &fnw, Real &del, int &nfval, int &ngrad, int &flagTR, const Vector< Real > &s, const Real snorm, const Real fold, const Vector< Real > &g, Objective< Real > &obj, Teuchos::RCP< Secant< Real > > &secant=Teuchos::null)
- void **run** (Vector< Real > &s, Real &snorm, Real &del, int &iflag, int &iter, const Vector< Real > &x, const Vector< Real > &grad, const Real &gnorm, Objective< Real > &obj, Teuchos::RCP< Secant< Real > > &secant=Teuchos::null)
- void **cauchy**point (Vector< Real > &s, Real &snorm, Real &del, int &iflag, int &iter, const Vector< Real > &x, const Vector< Real > &grad, const Real &gnorm, Objective< Real > &obj, Teuchos::RCP< Secant< Real > > &secant=Teuchos::null)
- void **truncatedCG** (Vector< Real > &s, Real &snorm, Real &del, int &iflag, int &iter, const Vector< Real > &x, const Vector< Real > &grad, const Real &gnorm, Objective< Real > &obj, Teuchos::RCP< Secant< Real > > &secant=Teuchos::null)
- void **dogleg** (Vector< Real > &s, Real &snorm, Real &del, int &iflag, int &iter, const Vector< Real > &x, const Vector< Real > &grad, const Real &gnorm, Objective< Real > &obj, Teuchos::RCP< Secant< Real > > &secant=Teuchos::null)
- void **doubledogleg** (Vector< Real > &s, Real &snorm, Real &del, int &iflag, int &iter, const Vector< Real > &x, const Vector< Real > &grad, const Real &gnorm, Objective< Real > &obj, Teuchos::RCP< Secant< Real > > &secant=Teuchos::null)

Private Attributes

- ETrustRegion **etr_**
- bool **useSecantPrecond_**
- bool **useSecantHessVec_**
- int **maxit_**
- Real **tol1_**
- Real **tol2_**

- Real **delmin_**
- Real **delmax_**
- Real **eta0_**
- Real **eta1_**
- Real **eta2_**
- Real **gamma0_**
- Real **gamma1_**
- Real **gamma2_**
- Real **pRed_**
- Real **TRsafe_**
- Real **eps_**

5.29.1 Detailed Description

template<class Real> class ROL::TrustRegion< Real >

Provides interface for and implements trust-region subproblem solvers.

Definition at line 56 of file ROL_TrustRegion.hpp.

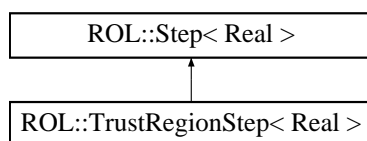
The documentation for this class was generated from the following file:

- ROL_TrustRegion.hpp

5.30 ROL::TrustRegionStep< Real > Class Template Reference

Provides the interface to compute optimization steps with trust regions.

#include <ROL_TrustRegionStep.hpp> Inheritance diagram for ROL::TrustRegionStep< Real >::



Public Member Functions

- **TrustRegionStep** (Teuchos::ParameterList &parlist)
- **TrustRegionStep** (Teuchos::RCP< [Secant](#)< Real > > &secant, Teuchos::ParameterList &parlist)
- void **initialize** (const [Vector](#)< Real > &x, [Objective](#)< Real > &obj, [AlgorithmState](#)< Real > &algo_state)
Initialize step.
- void **compute** ([Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj, [AlgorithmState](#)< Real > &algo_state)
Compute step.
- void **update** ([Vector](#)< Real > &x, const [Vector](#)< Real > &s, [Objective](#)< Real > &obj, [AlgorithmState](#)< Real > &algo_state)
Update step, if successful.
- std::string **printHeader** (void) const
Print iterate header.
- std::string **printName** (void) const
Print step name.
- std::string **print** ([AlgorithmState](#)< Real > &algo_state, bool printHeader=false) const
Print iterate status.

Private Attributes

- Teuchos::RCP< [Secant](#)< Real > > **secant_**
- Teuchos::RCP< [TrustRegion](#)< Real > > **trustRegion_**
- ETrustRegion **etr_**
- ESecant **esec_**
- bool **useSecantHessVec_**
- bool **useSecantPrecond_**
- Real **del_**
- std::vector< bool > **useInexact_**
- int **TRflag_**
- int **TR_nfval_**
- int **TR_ngrad_**
- int **CGflag_**
- int **CGiter_**

5.30.1 Detailed Description

template<class Real> class ROL::TrustRegionStep< Real >

Provides the interface to compute optimization steps with trust regions.

Definition at line 63 of file ROL_TrustRegionStep.hpp.

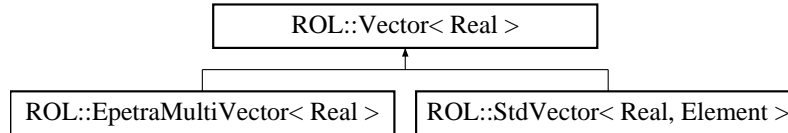
The documentation for this class was generated from the following file:

- ROL_TrustRegionStep.hpp

5.31 ROL::Vector< Real > Class Template Reference

Provides the vector space interface.

#include <ROL_Vector.hpp> Inheritance diagram for ROL::Vector< Real >::



Public Member Functions

- virtual void **plus** (const **Vector** &x)=0
*Compute $y \leftarrow x + y$ where $y = *this$.*
- virtual void **scale** (const Real alpha)=0
*Compute $y \leftarrow \alpha y$ where $y = *this$.*
- virtual Real **dot** (const **Vector** &x) const =0
*Returns $\langle y, x \rangle$ where $y = *this$.*
- virtual Real **norm** () const =0
*Returns $\|y\|$ where $y = *this$.*
- virtual Teuchos::RCP< **Vector** > **clone** () const =0
Clone to make a new (uninitialized) vector.
- virtual void **axpy** (const Real alpha, const **Vector** &x)
*Compute $y \leftarrow \alpha x + y$ where $y = *this$.*
- virtual void **zero** ()
Set to zero vector.
- virtual Teuchos::RCP< **Vector** > **basis** (const int i) const
Return i-th basis vector: define if finite-difference gradients and Hessians are used.
- virtual int **dimension** ()
Return dimension of the vector space.
- virtual void **set** (const **Vector** &x)
*Set $y \leftarrow x$ where $y = *this$.*

5.31.1 Detailed Description

template<class Real> class ROL::Vector< Real >

Provides the vector space interface. The basic interface to be supplied by the user includes:

- vector addition,
- scalar multiplication,
- dot (scalar) product of vectors,
- vector norm,
- cloning of vectors.

The dot product can represent an inner product (in Hilbert space) or a duality pairing (in general Banach space).

There are additional virtual member functions that the user may want to reimplement for added efficiency.

Definition at line 70 of file ROL_Vector.hpp.

The documentation for this class was generated from the following file:

- ROL_Vector.hpp

Chapter 6

File Documentation

6.1 example_01.cpp File Reference

Shows how to minimize Rosenbrock's function using Newton-Krylov. `#include "ROL_Rosenbrock.hpp"`

```
#include "ROL_LineSearchStep.hpp"
#include "ROL_Algorithm.hpp"
#include "Teuchos_oblackholestream.hpp"
#include "Teuchos_GlobalMPISession.hpp"
#include <iostream>
```

Defines

- `#define USE_HESSVEC 1`

Typedefs

- `typedef double RealT`

Functions

- `int main (int argc, char *argv[])`

6.1.1 Detailed Description

Shows how to minimize Rosenbrock's function using Newton-Krylov.

Definition in file [example_01.cpp](#).

6.2 ROL_Beale.hpp File Reference

Contains definitions for Beale's function. `#include "ROL_StdVector.hpp"`

`#include "ROL_Objective.hpp"`

Classes

- class [ROL::Objective_Beale< Real >](#)
Beale's function.

Defines

- `#define USE_HESSVEC 1`

Functions

- `template<class Real >`
`void ROL::getBeale (Teuchos::RCP< Objective< Real > > &obj, Vector<`
`Real > &x0, Vector< Real > &x)`

6.2.1 Detailed Description

Contains definitions for Beale's function.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_Beale.hpp](#).

6.3 ROL_FreudensteinRoth.hpp File Reference

Contains definitions for Freudenstein and Roth's function. `#include "ROL_StdVector.hpp"`

`#include "ROL_Objective.hpp"`

Classes

- class [ROL::Objective_FreudensteinRoth< Real >](#)
Freudenstein and Roth's function.

Functions

- `template<class Real >`
`void ROL::getFreudensteinRoth (Teuchos::RCP< Objective< Real > >`
`&obj, Vector< Real > &x0, Vector< Real > &x)`

6.3.1 Detailed Description

Contains definitions for Freudenstein and Roth's function.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_FreudensteinRoth.hpp](#).

6.4 ROL_LeastSquares.hpp File Reference

Contains definitions for least squares function. `#include "ROL_StdVector.hpp"`

`#include "ROL_Objective.hpp"`

Classes

- class [ROL::Objective_LeastSquares< Real >](#)
Least squares function.

Functions

- `template<class Real >`
void **ROL::getLeastSquares** (Teuchos::RCP< Objective< Real > > &obj,
Vector< Real > &x0, Vector< Real > &x)

6.4.1 Detailed Description

Contains definitions for least squares function.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_LeastSquares.hpp](#).

6.5 ROL_PoissonControl.hpp File Reference

Contains definitions for Poisson optimal control. `#include "ROL_StdVector.hpp"`

`#include "ROL_Objective.hpp"`

Classes

- class [ROL::Objective_PoissonControl< Real >](#)
Poisson distributed control.

Functions

- `template<class Real >`
void **ROL::getPoissonControl** (Teuchos::RCP< Objective< Real > > &obj,
Vector< Real > &x0, Vector< Real > &x)

6.5.1 Detailed Description

Contains definitions for Poisson optimal control.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_PoissonControl.hpp](#).

6.6 ROL_PoissonInversion.hpp File Reference

Contains definitions for Poisson material inversion. `#include "ROL_StdVector.hpp"`

`#include "ROL_Objective.hpp"`

`#include "Teuchos_LAPACK.hpp"`

Classes

- class [ROL::Objective_PoissonInversion< Real >](#)
Poisson material inversion.

Functions

- `template<class Real >`
void **ROL::getPoissonInversion** (Teuchos::RCP< Objective< Real > > &obj,
Vector< Real > &x0, Vector< Real > &x)

6.6.1 Detailed Description

Contains definitions for Poisson material inversion.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_PoissonInversion.hpp](#).

6.7 ROL_Powell.hpp File Reference

Contains definitions for Powell's badly scaled function. `#include "ROL_StdVector.hpp"`

`#include "ROL_Objective.hpp"`

Classes

- class [ROL::Objective_Powell< Real >](#)
Powell's badly scaled function.

Functions

- `template<class Real >`
`void ROL::getPowell (Teuchos::RCP< Objective< Real > > &obj, Vector< Real > &x0, Vector< Real > &x)`

6.7.1 Detailed Description

Contains definitions for Powell's badly scaled function.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_Powell.hpp](#).

6.8 ROL_Rosenbrock.hpp File Reference

Contains definitions for Rosenbrock's function. `#include "ROL_StdVector.hpp"`
`#include "ROL_Objective.hpp"`

Classes

- class [ROL::Objective_Rosenbrock< Real >](#)
Rosenbrock's function.

Functions

- `template<class Real >`
void **ROL::getRosenbrock** (Teuchos::RCP< Objective< Real > > &obj,
Vector< Real > &x0, Vector< Real > &x)

6.8.1 Detailed Description

Contains definitions for Rosenbrock's function.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_Rosenbrock.hpp](#).

6.9 ROL_SumOfSquares.hpp File Reference

Contains definitions for sum of squares function. `#include "ROL_StdVector.hpp"`

`#include "ROL_Objective.hpp"`

Classes

- class [ROL::Objective_SumOfSquares< Real >](#)
Sum of squares function.

Functions

- `template<class Real >`
`void ROL::getSumOfSquares (Teuchos::RCP< Objective< Real > > &obj,`
`Vector< Real > &x0, Vector< Real > &x)`

6.9.1 Detailed Description

Contains definitions for sum of squares function.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_SumOfSquares.hpp](#).

6.10 ROL_TestObjectives.hpp File Reference

Contains definitions of test objective functions. `#include "ROL_Rosenbrock.hpp"`

`#include "ROL_FreudensteinRoth.hpp"`

`#include "ROL_Beale.hpp"`

`#include "ROL_Powell.hpp"`

`#include "ROL_SumOfSquares.hpp"`

`#include "ROL_LeastSquares.hpp"`

`#include "ROL_PoissonControl.hpp"`

`#include "ROL_PoissonInversion.hpp"`

`#include "ROL_Types.hpp"`

`#include "ROL_StdVector.hpp"`

`#include "ROL_Objective.hpp"`

Functions

- `template<class Real >`
void **ROL::getTestObjectives** (Teuchos::RCP< Objective< Real > > &obj,
Vector< Real > &x0, Vector< Real > &x, const ETestObjectives test)

6.10.1 Detailed Description

Contains definitions of test objective functions.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_TestObjectives.hpp](#).

6.11 ROL_Types.hpp File Reference

Contains definitions of custom data types in ROL. `#include <Teuchos_ScalarTraits.hpp>`

`#include <Teuchos_TestForException.hpp>`

Defines

- `#define ROL_VALIDATE(A)`
- `#define ROL_NUM_CHECKDERIV_STEPS 13`

Number of steps for derivative checks.

Enumerations

- `enum EDescent {`
`DESCENT_STEEPEST = 0, DESCENT_NONLINEARCG, DESCENT-`
`SECANT, DESCENT_NEWTON,`
`DESCENT_NEWTONKRYLOV, DESCENT_SECANTPRECOND,`
`DESCENT_LAST }`

Enumeration of descent direction types.

- `enum ESecant {`
`SECANT_LBFGS = 0, SECANT_LDFF, SECANT_LSR1, SECANT-`
`BARZILAIBORWEIN,`
`SECANT_USERDEFINED, SECANT_LAST }`

Enumeration of secant update algorithms.

- `enum ENonlinearCG {`
`NONLINEARCG_HESTENES_STIEFEL = 0, NONLINEARCG-`
`FLETCHER_REEVES, NONLINEARCG_DANIEL, NONLINEARCG-`
`POLAK_RIBIERE,`
`NONLINEARCG_FLETCHER_CONJDESC, NONLINEARCG_LIU-`
`STOREY, NONLINEARCG_DAI_YUAN, NONLINEARCG_HAGAR-`
`ZHANG,`
`NONLINEARCG_LAST }`

Enumeration of nonlinear CG algorithms.

- enum **ELineSearch** {
LINESEARCH_BACKTRACKING = 0, **LINESEARCH_BISECTION**,
LINESEARCH_GOLDENSECTION, **LINESEARCH_CUBICINTERP**,
LINESEARCH_BRENDS, **LINESEARCH_LAST** }

Enumeration of line-search types.

- enum **ECurvatureCondition** { **CURVATURECONDITION_-**
WOLFE = 0, **CURVATURECONDITION_STRONGWOLFE**,
CURVATURECONDITION_GOLDSTEIN, **CURVATURECONDITION_-**
LAST }

Enumeration of line-search curvature conditions.

- enum **ETrustRegion** {
TRUSTREGION_CAUCHYPOINT = 0, **TRUSTREGION_-**
TRUNCATEDCG, **TRUSTREGION_DOGLEG**, **TRUSTREGION_-**
DOUBLEDOGLEG,
TRUSTREGION_LAST }

Enumeration of trust-region solver types.

- enum **ETestObjectives** {
TESTOBJECTIVES_ROSENBROCK = 0, **TESTOBJECTIVES_-**
FREUDENSTEINANDROTH, **TESTOBJECTIVES_BEALE**,
TESTOBJECTIVES_POWELL,
TESTOBJECTIVES_SUMOFSQUARES, **TESTOBJECTIVES_-**
LEASTSQUARES, **TESTOBJECTIVES_POISSONCONTROL**,
TESTOBJECTIVES_POISSONINVERSION,
TESTOBJECTIVES_LAST }

Enumeration of test objective functions.

Functions

- std::string **ROL::EDescentToString** (EDescent tr)
- int **ROL::IsValidDescent** (EDescent d)
Verifies validity of a [Secant](#) enum.
- EDescent & **ROL::operator++** (EDescent &type)
- EDescent **ROL::operator++** (EDescent &type, int)
- EDescent & **ROL::operator--** (EDescent &type)
- EDescent **ROL::operator--** (EDescent &type, int)
- std::string **ROL::ESecantToString** (ESecant tr)

- int [ROL::isValidSecant](#) (ESecant s)

Verifies validity of a [Secant](#) enum.

- ESecant & **ROL::operator++** (ESecant &type)
- ESecant **ROL::operator++** (ESecant &type, int)
- ESecant & **ROL::operator--** (ESecant &type)
- ESecant **ROL::operator--** (ESecant &type, int)
- std::string **ROL::ENonlinearCGToString** (ENonlinearCG tr)
- int [ROL::isValidNonlinearCG](#) (ENonlinearCG s)

Verifies validity of a [NonlinearCG](#) enum.

- ENonlinearCG & **ROL::operator++** (ENonlinearCG &type)
- ENonlinearCG **ROL::operator++** (ENonlinearCG &type, int)
- ENonlinearCG & **ROL::operator--** (ENonlinearCG &type)
- ENonlinearCG **ROL::operator--** (ENonlinearCG &type, int)
- std::string **ROL::ELineSearchToString** (ELineSearch ls)
- int [ROL::isValidLineSearch](#) (ELineSearch ls)

Verifies validity of a [LineSearch](#) enum.

- ELineSearch & **ROL::operator++** (ELineSearch &type)
- ELineSearch **ROL::operator++** (ELineSearch &type, int)
- ELineSearch & **ROL::operator--** (ELineSearch &type)
- ELineSearch **ROL::operator--** (ELineSearch &type, int)
- std::string **ROL::ECurvatureConditionToString** (ECurvatureCondition ls)
- int [ROL::isValidCurvatureCondition](#) (ECurvatureCondition ls)

Verifies validity of a [CurvatureCondition](#) enum.

- ECurvatureCondition & **ROL::operator++** (ECurvatureCondition &type)
- ECurvatureCondition **ROL::operator++** (ECurvatureCondition &type, int)
- ECurvatureCondition & **ROL::operator--** (ECurvatureCondition &type)
- ECurvatureCondition **ROL::operator--** (ECurvatureCondition &type, int)
- std::string **ROL::ETrustRegionToString** (ETrustRegion tr)
- int [ROL::isValidTrustRegion](#) (ETrustRegion ls)

Verifies validity of a [TrustRegion](#) enum.

- ETrustRegion & **ROL::operator++** (ETrustRegion &type)
- ETrustRegion **ROL::operator++** (ETrustRegion &type, int)
- ETrustRegion & **ROL::operator--** (ETrustRegion &type)
- ETrustRegion **ROL::operator--** (ETrustRegion &type, int)
- std::string **ROL::ETestObjectivesToString** (ETestObjectives to)
- int [ROL::isValidTestObjectives](#) (ETestObjectives to)

Verifies validity of a [TestObjectives](#) enum.

- ETestObjectives & **ROL::operator++** (ETestObjectives &type)
- ETestObjectives **ROL::operator++** (ETestObjectives &type, int)
- ETestObjectives & **ROL::operator--** (ETestObjectives &type)
- ETestObjectives **ROL::operator--** (ETestObjectives &type, int)

Variables

- static const double [ROL::ROL_EPSILON](#) =
std::abs(Teuchos::ScalarTraits<double>::eps())
Platform-dependent machine epsilon.
- static const double [ROL::ROL_THRESHOLD](#) = 10.0 * ROL_EPSILON
Tolerance for various equality tests.

6.11.1 Detailed Description

Contains definitions of custom data types in ROL.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_Types.hpp](#).

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